

IMACS

INGÉNIERIE MATHÉMATIQUE

& CALCUL SCIENTIFIQUE

**RETARDED POTENTIAL METHOD FOR NON-HOMOGENEOUS MEDIA AND
APPROXIMATION OF THIN LAYERS BY GENERALIZED IMPEDANCE
CONDITIONS IN ELECTRO-MAGNETICS.**

Toni SAYAH

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 - b) Integral representation
 - c) Variational formulation
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 - f) Numerical convolution system
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 - b) Integral representation

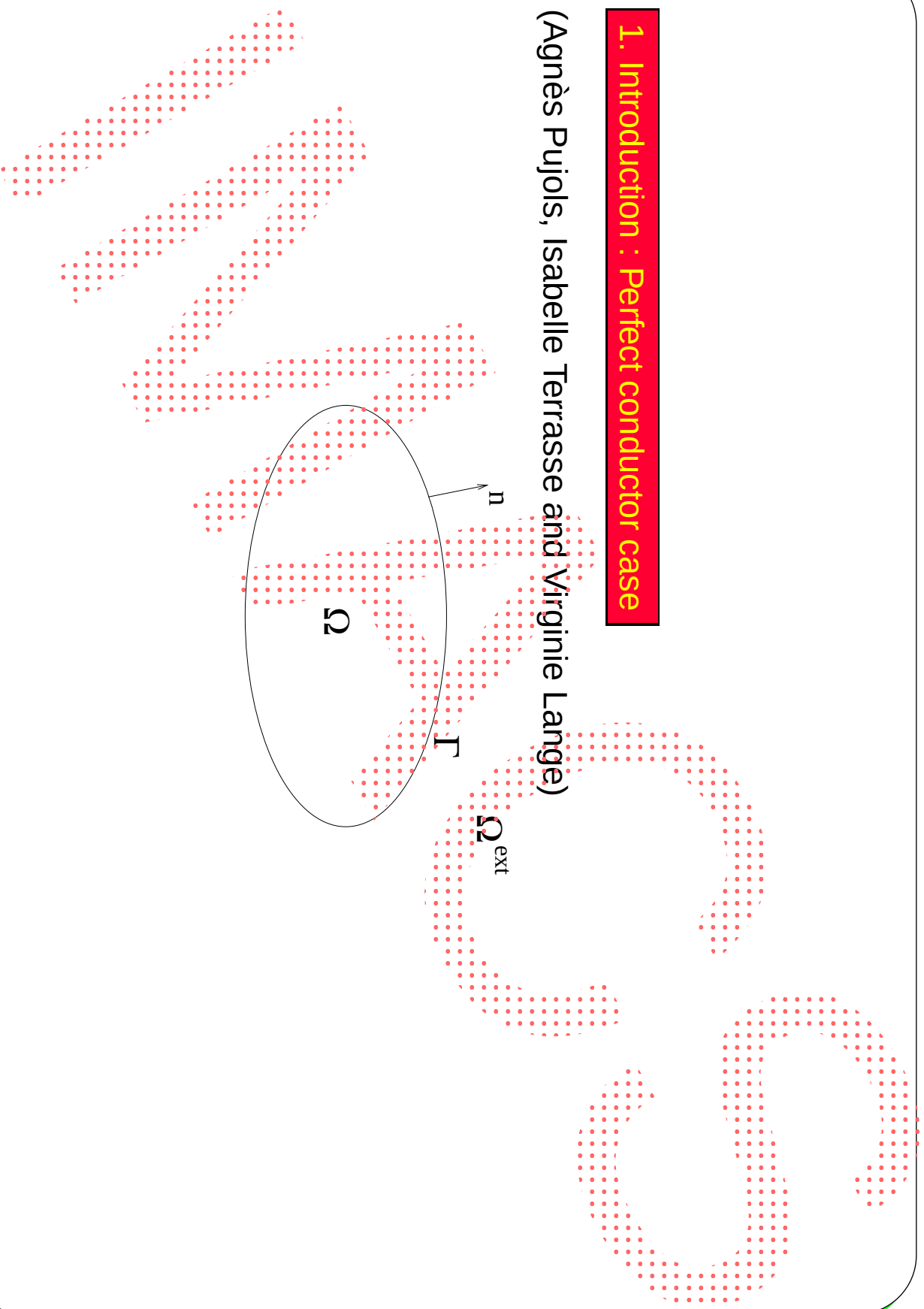
- c) First application : Approximation of “Engquist-Nédélec” for thin layers
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1. Introduction : Perfect conductor case

(Agnès Pujols, Isabelle Terrasse and Virginie Lange)



a. Maxwell Equations

$\vec{E}^i(t, x)$ incident electrical wave

$\vec{E}^d(t, x)$ diffracted electrical wave (causal : $=0$ for $t \leq 0$)

$\vec{E}(t, x)$ total electrical wave

$$\left\{ \begin{array}{ll} \vec{\text{curl}} \vec{E}^d(t, x) + \mu_0 \frac{\partial \vec{H}^d}{\partial t}(t, x) = \vec{0} & \text{for } (t, x) \in \mathbb{R} \times \Omega^{ext} \\ \vec{\text{curl}} \vec{H}^d(t, x) - \epsilon_0 \frac{\partial \vec{E}^d}{\partial t}(t, x) = \vec{0} & \text{for } (t, x) \in \mathbb{R} \times \Omega^{ext} \\ \vec{E}^d(t, x) \wedge \vec{n}(x) = -\vec{E}^i(t, x) \wedge \vec{n}(x) & \text{for } (t, x) \in \mathbb{R} \times \Gamma \end{array} \right.$$

b. Integral representation

we prolong the diffracted wave by $-\vec{E}^i$ in Ω . for $t \in \mathbb{R}$ and $x \in \Omega \cup \Omega^{ext}$, we have

$$\left\{ \begin{aligned} \vec{E}^d(t, x) = & \quad \nabla \int_{\Gamma} \frac{1}{4\pi\epsilon_0 r} \int_0^{t-r/c} \operatorname{div}_{\Gamma} \vec{j}(\tau, y) d\tau d\Gamma_y \\ & - \frac{\partial}{\partial t} \int_{\Gamma} \frac{\mu_0}{4\pi r} \vec{j}(t-r/c, y) d\Gamma_y \\ \vec{H}^d(t, x) = & \quad \vec{\operatorname{curl}} \int_{\Gamma} \frac{1}{4\pi r} \vec{j}(t-r/c, y) d\Gamma_y \end{aligned} \right.$$

where $r = |x - y|$, $\vec{j}$ the electrical surface current defined by

$$\vec{j} = [\vec{H}^d \wedge \vec{n}] = (-\vec{H}^i - \vec{H}^d) \wedge \vec{n}$$

c. Variational formulation

For $\vec{E}^i \wedge \vec{n} \in H_\sigma^{3/2}(\mathbb{R}_+, TH^{-1/2}(\text{div}, \Gamma))$,

Find $\vec{j}$ in $V = H_\sigma^{1/2}(\mathbb{R}_+, TH^{-1/2}(\text{div}, \Gamma))$ such that $\forall \vec{j}^t \in V$

$$\left\{ \begin{aligned} & \int_{\mathbb{R}} e^{-2\sigma t} \int_{\Gamma \times \Gamma} \frac{1}{4\pi \varepsilon_0 r} \text{div}_\Gamma \left(\int_0^{t-r/c} \vec{j}(\tau, y) d\tau \right) \text{div}_\Gamma \vec{j}^t(t, x) d\Gamma_y d\Gamma_x dt \\ & - \int_{\mathbb{R}} e^{-2\sigma t} \int_{\Gamma \times \Gamma} \frac{\mu_0}{4\pi r} \frac{\partial \vec{j}}{\partial t} (t - r/c, y) \cdot \vec{j}^t(t, x) d\Gamma_y d\Gamma_x dt \\ & = - \int_{\mathbb{R}} e^{-2\sigma t} \int_{\Gamma} \vec{E}^i(t, x) \cdot \vec{j}^t(t, x) d\Gamma_x dt \end{aligned} \right.$$

Existence and Uniqueness (l. TERRASSE).

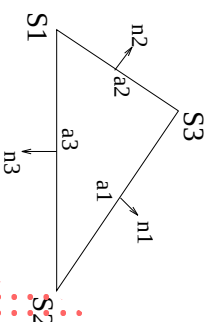
d. Theoretical Ingredients

The proof of the theoretical makes use of the following steps :

- Fourier-Laplace transformation : we obtain a frequency problem with a complex frequency.
- studying the frequency problem : coercivity of the sesquilinear form, continuity estimation with the indexed norms.
- Paley-Wiener theorem : we return to the time domain.

Attention : bilinear form in the time domain is continuous and coercive in different spaces. We can not apply the Lax-Milgram theorem to prove the theoretical results. We study the problem in the frequency domain.

e. Finite Element



$$\vec{j}(t, x) = \sum_{n \geq 1} \vec{j}^n(x) \beta^n(t) = \sum_{n \geq 1} \beta^n(t) \sum_{T \in \tau_n} \sum_{i=1}^3 \lambda_{i,T}^n \vec{W}_{i,T}(x)$$

$$\vec{j}^t(t_n, x) = \vec{j}^t(x) \beta_0^n(t_n)$$

where

$$\beta^n(t) = \begin{cases} t - t_n & \text{for } t_n \leq t \leq t_{n+1} \\ 0 & \text{for } t < t_{n-1} \\ \Delta t & \text{for } t \geq t_{n+1} \end{cases}$$

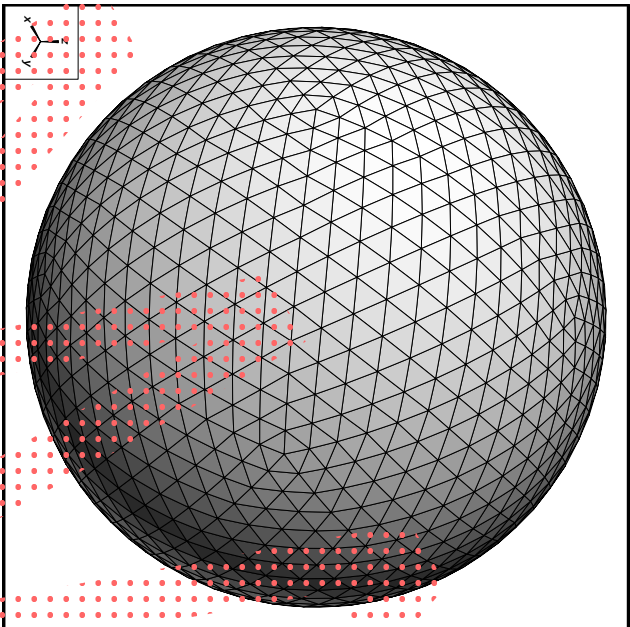
$$\beta_0^n(t_n) = \begin{cases} 1 & \text{for } t_n \leq t \leq t_{n+1} \\ 0 & \text{otherwise} \end{cases}$$

f. Numerical convolution system

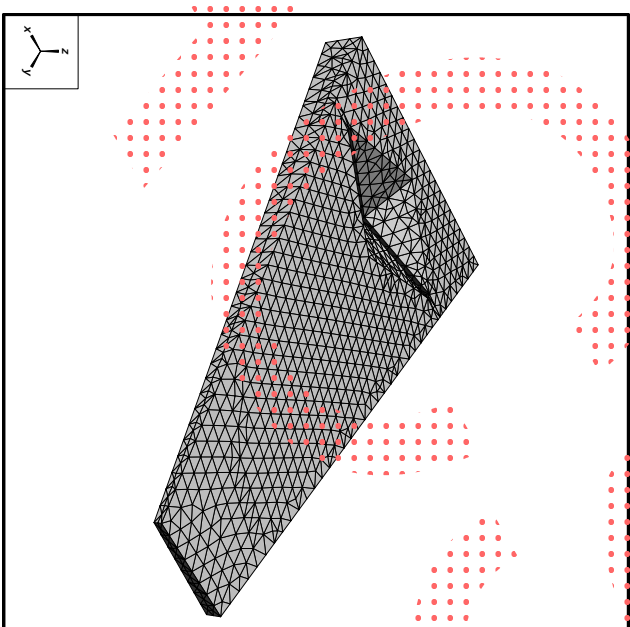
$$\sum_{k=0}^N A^k J^{n-k} = b^n$$

- A^k : The matrix of the interaction at distance $k\Delta t$.
- J^{n-k} : The vector of degrees of freedom at time $(n - k)\Delta t$.
- N : The number of matrices determined by Δt and the diameter of the obstacle.

g. Numerical results

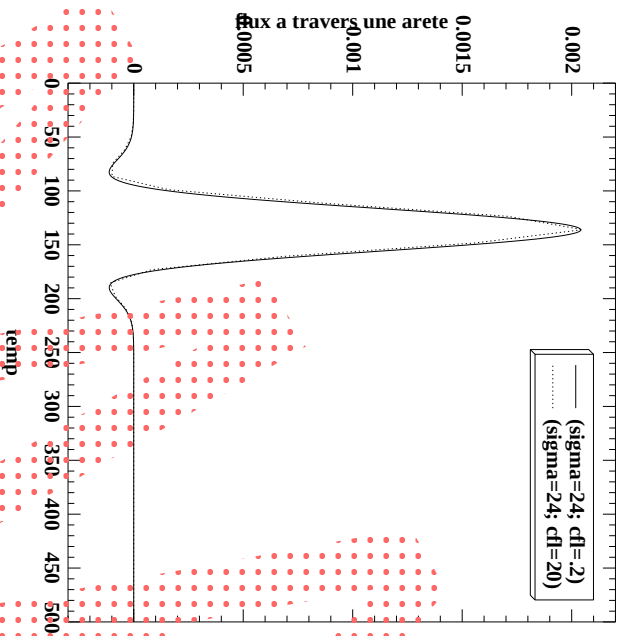


(a) sphere of 2880
triangles : $R = 1\text{cm}$.

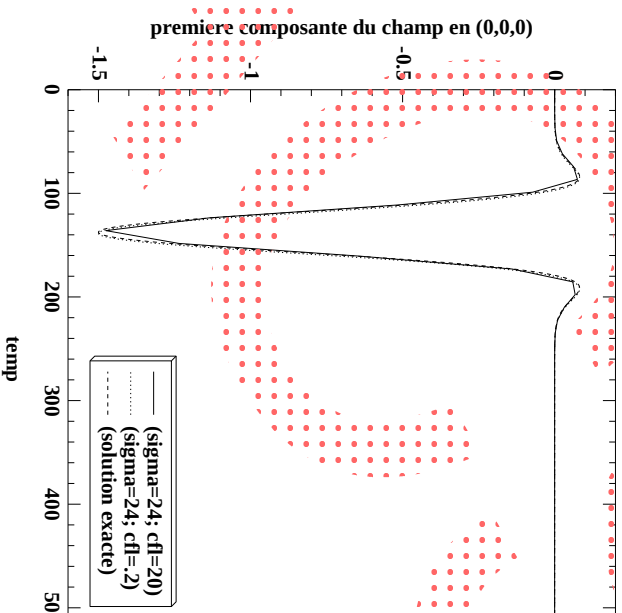


(b) cetaf (Dassault
Aviation) of 3594
triangles

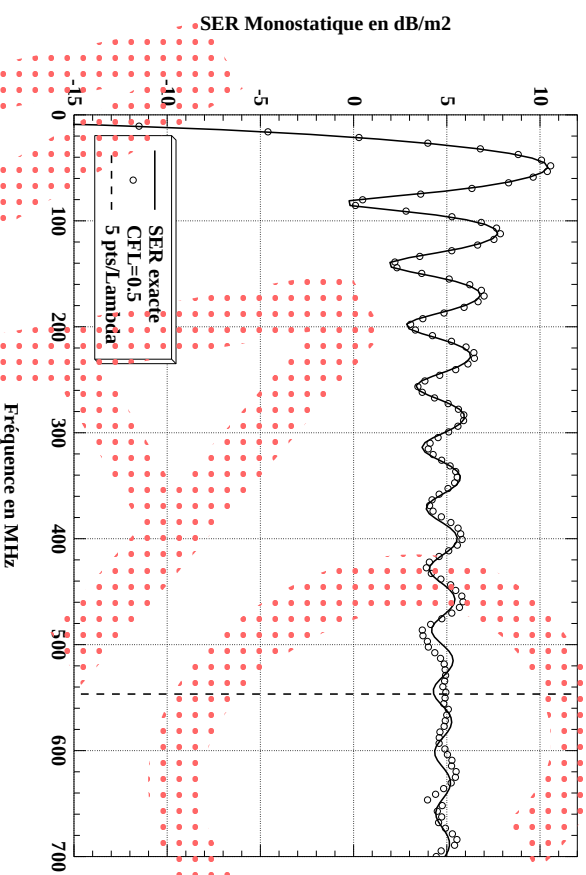
Numerical scheme (Unconditionally stable) : (sphere)



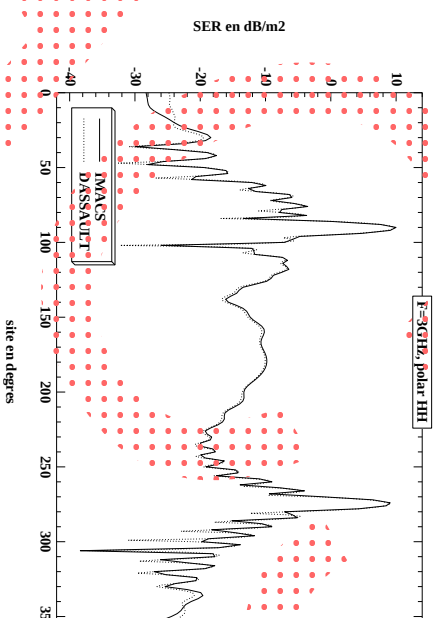
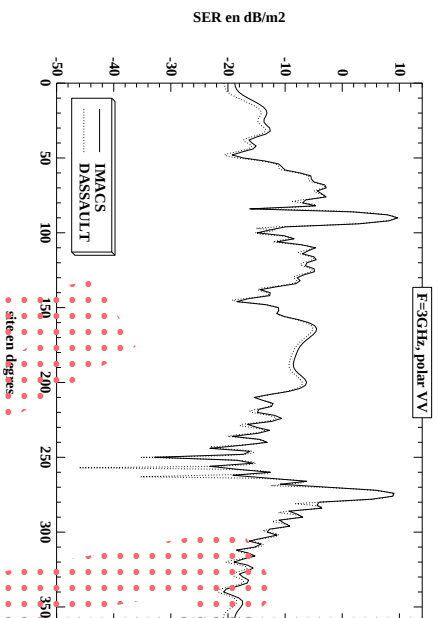
(c) Comparison : flux through an edge (cfl = 0.2 and 20)



(d) Comparison : solution at (0,0,0) (cfl = 0.2 and 20)

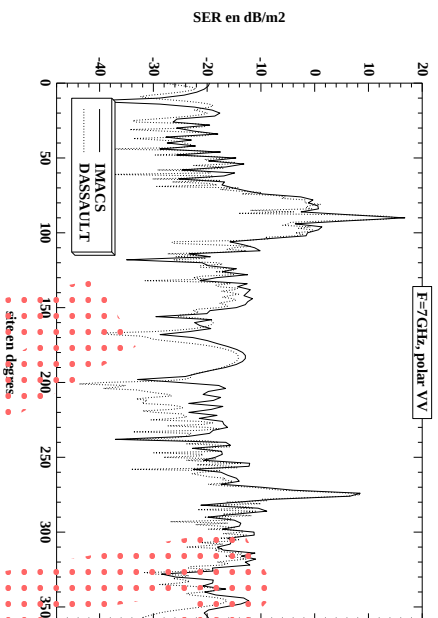


Comparison of the calculated monostatic RCS and the Mie
for the sphere ($cfl = 0.5$)

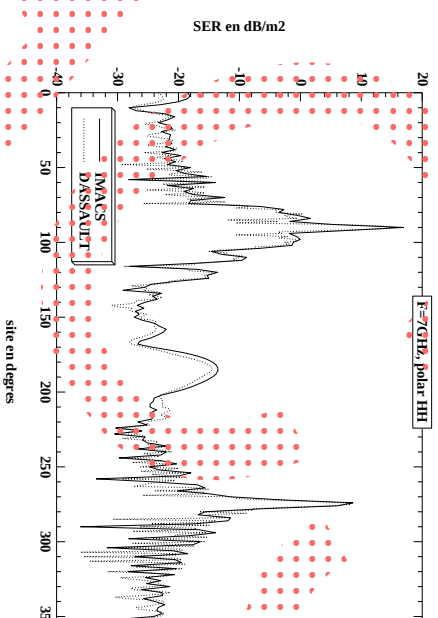


(e) Comparison of
the bistatic RCS
(VV polarization) ;
freq. = 3Ghz

(f) Comparison of
the bistatic RCS
(HH polarization) ;
freq. = 3Ghz



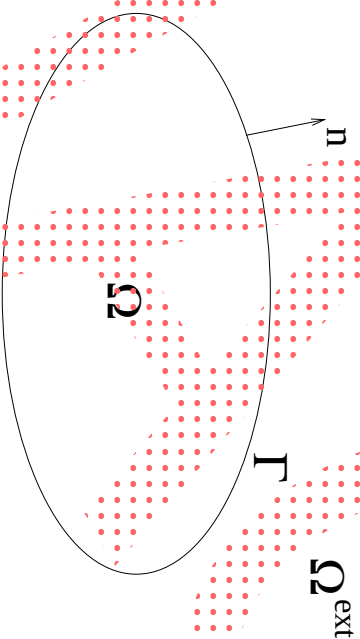
(g) Comparison of
the bistatic RCS
(VV polarization) ;
freq. = 7Ghz



(h) Comparison of
the bistatic RCS
(HH polarization) ;
freq. = 7Ghz

2. Generalized impedance conditions

- Virginie LANGE ($Z = \text{constant}$)



a. MAXWELL Equations

$$\begin{cases} \vec{\text{curl}} \vec{E}(t, x) + \mu_0 \frac{\partial \vec{H}}{\partial t}(t, x) = \vec{0} & \text{for } (t, x) \in \mathbb{R} \times \Omega^{ext} \\ \vec{\text{curl}} \vec{H}(t, x) - \varepsilon_0 \frac{\partial \vec{E}}{\partial t}(t, x) = \vec{0} & \text{for } (t, x) \in \mathbb{R} \times \Omega^{ext} \\ \vec{E}_{||}(t, x) = Z_{t,x}(\vec{H} \wedge \vec{n}) & \text{for } (t, x) \in \mathbb{R} \times \Gamma \end{cases}$$

b. Integral representation

we prolong the diffracted wave $\vec{E}^d$ by $-\vec{E}^i$ in Ω .

$$\begin{aligned} \vec{E}(t, x) = & \vec{E}^i(t, x) + \vec{\nabla} \int_{\Gamma} \frac{\int_0^{t-r/c} \operatorname{div}_{\Gamma} \vec{j}(\tau, y) d\tau}{4\epsilon_0 \pi r} d\Gamma_y \\ & - \mu_0 \frac{\partial}{\partial t} \int_{\Gamma} \frac{\vec{j}(t-r/c, y)}{4\mu_0 \pi r} d\Gamma_y - \operatorname{curl} \int_{\Gamma} \frac{\vec{m}(t-r/c, y)}{4\pi r} d\Gamma_y \\ \vec{H}(t, x) = & \vec{H}^i(t, x) + \vec{\nabla} \int_{\Gamma} \frac{\int_0^{t-r/c} \operatorname{div}_{\Gamma} \vec{m}(\tau, y) d\tau}{4\mu_0 \pi r} d\Gamma_y \\ & - \epsilon_0 \frac{\partial}{\partial t} \int_{\Gamma} \frac{\vec{m}(t-r/c, y)}{4\pi r} d\Gamma_y + \operatorname{curl} \int_{\Gamma} \frac{\vec{j}(t-r/c, y)}{4\pi r} d\Gamma_y \end{aligned}$$

where $r = |x - y|$, $\vec{j}$ and $\vec{m}$ the surface currents defined by $\vec{j} = [\vec{H}^d \wedge \vec{n}] = (-\vec{H}^i - \vec{H}^d) \wedge \vec{n}$ and $\vec{m} = [\vec{n} \wedge \vec{E}] = \vec{E} \wedge \vec{n}$

Definition of some surface operators : (simplify the formulas)

$$\begin{cases} P_t^1(\vec{j}) = \frac{1}{\varepsilon_0} \vec{\nabla}_\Gamma \int_\Gamma \frac{\int_0^{t-r/c} \operatorname{div}_\Gamma \vec{j}(\tau, y) d\tau}{4\pi r} d\Gamma_y - \mu_0 \Pi_x \frac{\partial}{\partial t} \int_\Gamma \frac{\vec{j}(t-r/c, y)}{4\pi r} d\Gamma_y \\ P_t^2(\vec{j}) = -\Pi_x \int_\Gamma \nabla_x \left(\frac{1}{r} \right) \wedge \left(\vec{j}(t-r/c, y) + \frac{r}{c} \frac{\partial \vec{j}}{\partial t}(t-r/c, y) \right) d\Gamma_y \end{cases}$$

First problem

$$(S) \quad \left\{ \begin{array}{ll} \text{Find } \vec{j} \text{ and } \vec{m} \text{ causal, such that} & \\ -Z_{t,x}(\vec{j}) + \frac{\vec{m} \wedge \vec{n}}{2} = \vec{E}_\Gamma^i + P_t^1(\vec{j}) + P_t^2(\vec{m}) & \text{on } \mathbb{R} \times \Gamma \\ \frac{\vec{j} \wedge \vec{n}}{2} = \vec{H}_\Gamma^i + \frac{\varepsilon_0}{\mu_0} P_t^1(\vec{m}) - P_t^2(\vec{j}) & \text{on } \mathbb{R} \times \Gamma \end{array} \right.$$

Second problem : we denote $Z_{t,x}^{-1}$ the inverse operator of $Z_{t,x}$

Find $\vec{j}$ and $\vec{m}$ causal, such that

$$(c) \quad \left\{ \begin{array}{ll} -\frac{Z_{t,x}(\vec{j})}{2} = \vec{E}_\Gamma^i + P_t^1(\vec{j}) + P_t^2(\vec{m}) & \text{on } \mathbb{R} \times \Gamma \\ \frac{\vec{n} \wedge Z_{t,x}^{-1}(\vec{n} \wedge \vec{m})}{2} = \vec{H}_\Gamma^i + \frac{\varepsilon_0}{\mu_0} P_t^1(\vec{m}) - P_t^2(\vec{j}) & \text{on } \mathbb{R} \times \Gamma \end{array} \right.$$

Definition of the bilinear forms b_Γ , b_t^s , b_t^c , and L_t

$$b_\Gamma(\vec{j}, \vec{m}, \vec{j}^t, \vec{m}^t) = \langle P_t^1(\vec{j}), \vec{j}^t \rangle_{\sigma, \Gamma} + \langle P_t^2(\vec{m}), \vec{j}^t \rangle_{\sigma, \Gamma} + \frac{\varepsilon_0}{\mu_0} \langle P_t^1(\vec{m}), \vec{j}^t \rangle_{\sigma, \Gamma} - \langle P_t^2(\vec{j}), \vec{m}^t \rangle_{\sigma, \Gamma}$$

$$b_t^s(\vec{j}, \vec{m}, \vec{j}^t, \vec{m}^t) = b_\Gamma(\vec{j}, \vec{m}, \vec{j}^t, \vec{m}^t) - \frac{1}{2} \langle \vec{j} \wedge \vec{n}, \vec{m}^t \rangle_{\sigma, \Gamma} + \langle Z_{t,x}(\vec{j}), \vec{j}^t \rangle_{\sigma, \Gamma} - \frac{1}{2} \langle \vec{m} \wedge \vec{n}, \vec{j}^t \rangle_{\sigma, \Gamma}$$

$$b_t^c(\vec{j}, \vec{m}, \vec{j}^t, \vec{m}^t) = b_\Gamma(\vec{j}, \vec{m}, \vec{j}^t, \vec{m}^t) + \frac{1}{2} \langle Z_{t,x}(\vec{j}), \vec{j}^t \rangle_{\sigma, \Gamma} + \frac{1}{2} \langle Z_{t,x}^{-1}(\vec{n} \wedge \vec{m}), (\vec{n} \wedge \vec{m}^t) \rangle_{\sigma, \Gamma}$$

$$L_t(\vec{j}^t, \vec{m}^t) = -\langle \vec{E}^i, \vec{j}^t \rangle_{\sigma, \Gamma} - \langle \vec{H}^i, \vec{m}^t \rangle_{\sigma, \Gamma}$$

with
$$\langle \vec{j}, \vec{j}^t \rangle_{\sigma, \Gamma} = \int_{\mathbb{R}} \int_{\Gamma} e^{-2\sigma t} \vec{j} \cdot \vec{j}^t d\Gamma dt$$

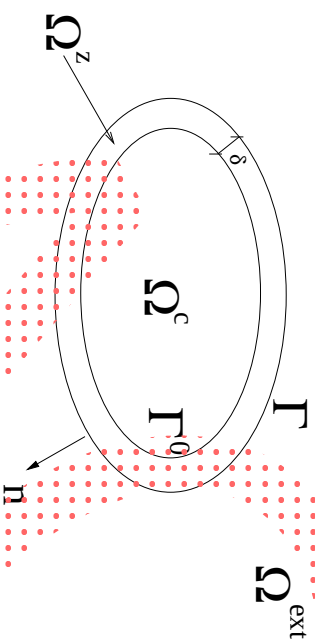
Variational problem associated to (S)

$$^{(S_v)} \left\{ \begin{array}{l} \text{Find } (\vec{j}, \vec{m}) \in V_{t,j}^s \times V_{t,m}^s \text{ such that } \forall (\vec{j}^t, \vec{m}^t) \in V_{t,j}^s \times V_{t,m}^s \\ b_t^s(\vec{j}, \vec{m}, \vec{j}^t, \vec{m}^t) = L_t(\vec{j}^t, \vec{m}^t) \end{array} \right.$$

Variational problem associated to (C)

$$^{(C_v)} \left\{ \begin{array}{l} \text{Find } (\vec{j}, \vec{m}) \in V_{t,j}^c \times V_{t,m}^c \text{ such that } \forall (\vec{j}^t, \vec{m}^t) \in V_{t,j}^c \times V_{t,m}^c \\ b_t^c(\vec{j}, \vec{m}, \vec{j}^t, \vec{m}^t) = L_t(\vec{j}^t, \vec{m}^t) \end{array} \right.$$

c. First application : Approximation of “Engquist-Nédélec” for thin layers



- the thickness δ is small.
- ε, μ : the characteristics of the dielectric layer.
- In frequency domain : $\mathcal{Z}_x(\vec{\mathcal{J}}) = \delta \left(-\frac{1}{i\omega\varepsilon} \nabla_{\Gamma} \operatorname{div}_{\Gamma}(\vec{\mathcal{J}}) + i\omega\mu\vec{\mathcal{J}} \right)$
- In time domain : $Z_{t,x}(\vec{j}) = \delta \left(\frac{1}{\varepsilon} \nabla_{\Gamma} \operatorname{div}_{\Gamma} \int_0^t \vec{j}(\tau, x) d\tau - \mu \frac{\partial \vec{j}}{\partial t}(t, x) \right)$

Spaces of $\vec{j}, \vec{m}$:

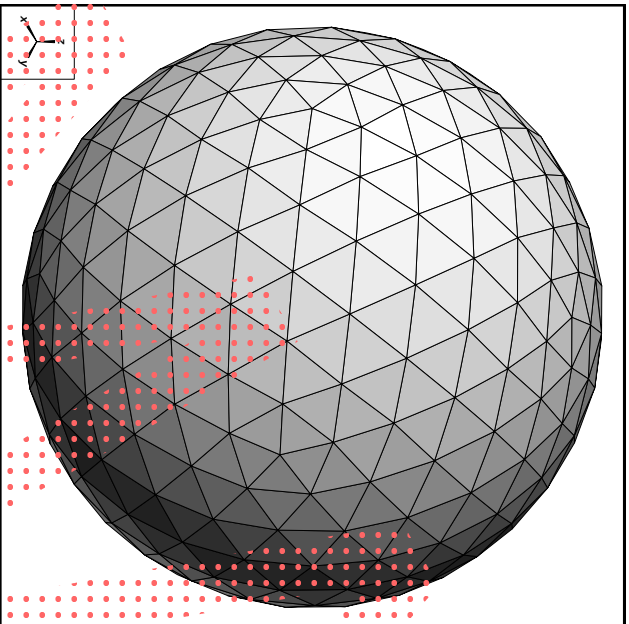
$$\begin{aligned}\vec{j} &\in V_{t,j}^s = H_o^{1/2}(\mathbb{R}_+, TH(div, \Gamma)) \\ \vec{m} &\in V_{t,m}^s = H_o^{1/2}(\mathbb{R}_+, TH^{-1/2}(div, \Gamma))\end{aligned}$$

Theorem : The problem (S_v) has a unique solution in $V_{t,j}^s \times V_{t,m}^s$. (Coercivity in the frequency domain transmitted to the time domain).

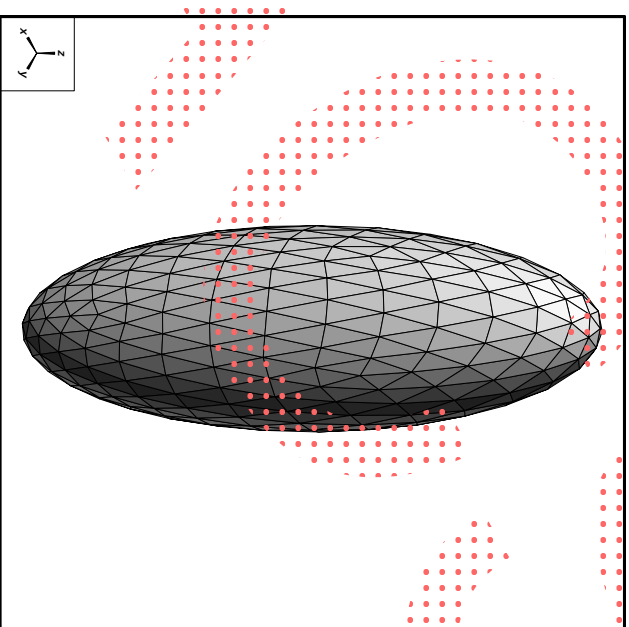
d. Numerical system (Unconditionally stable)

$$\sum_{k=0}^N A_1^k J^{n-k} + \sum_{k=0}^N C^k M^{n-k} = b_1^n$$
$$\sum_{k=0}^N A_2^k M^{n-k} + \sum_{k=0}^N C^k J^{n-k} = b_2^n$$

e. Numerical results

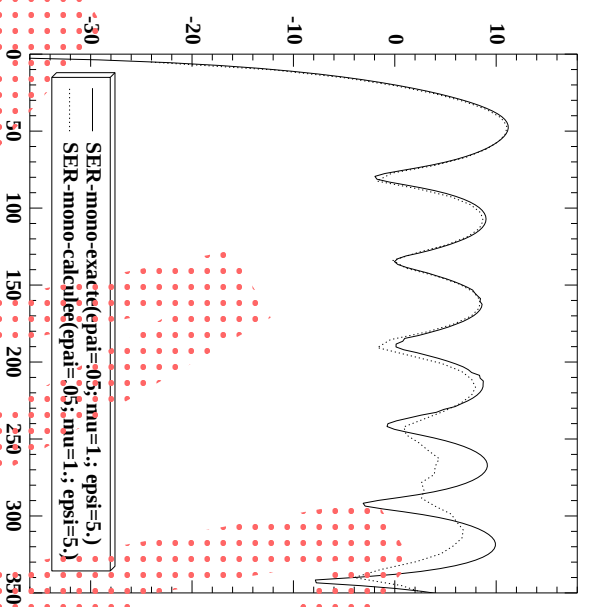


(i) sphere of 720
triangles : $R = 1.m.$

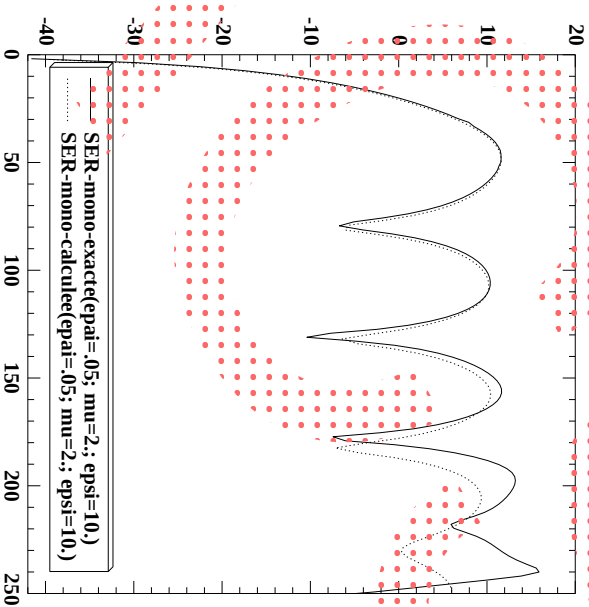


(i) ellipsoid ($.3m,$
 $.3m, 1.m$) de 720
triangles

f. Numerical results (sphere)

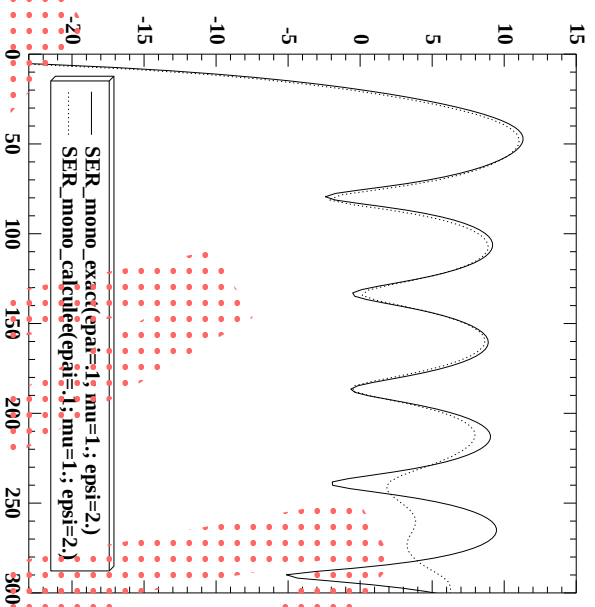


(k) $\delta=5\text{cm}$; $\epsilon_r=5$;
 $\mu_r=1$; $f_{5pt} = 118$
Mhz



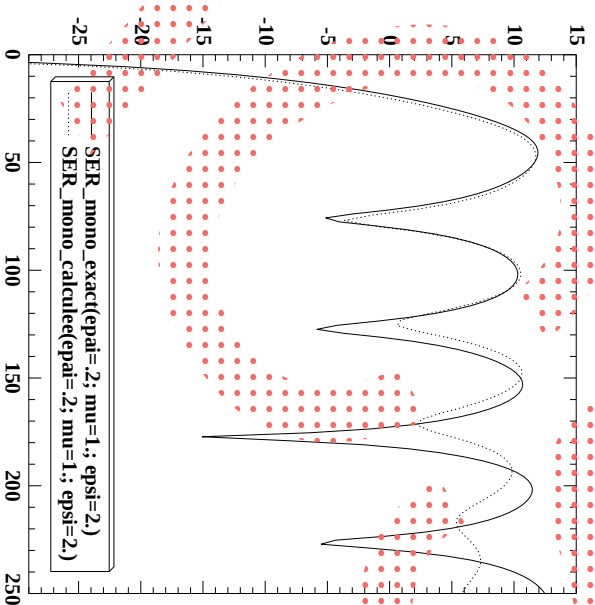
(l) $\delta=5\text{cm}$; $\epsilon_r=10$;
 $\mu_r=2$; $f_{5pt} = 56$ Mhz

Generalized impedance conditions



(m) $\delta=10\text{cm}$; $\epsilon_r=2$;

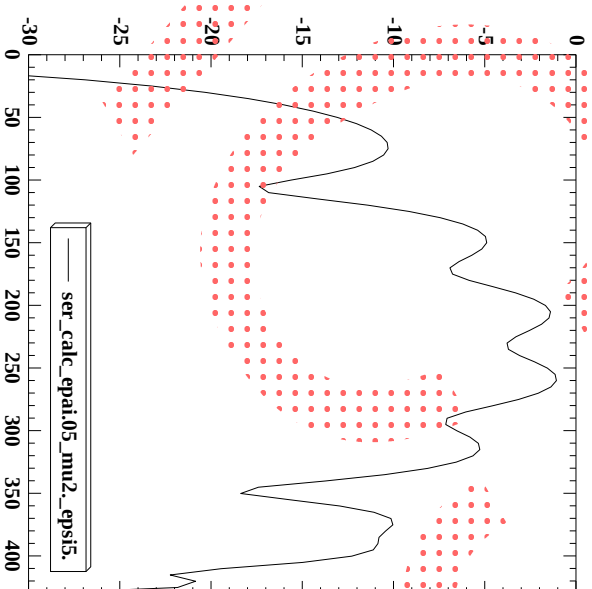
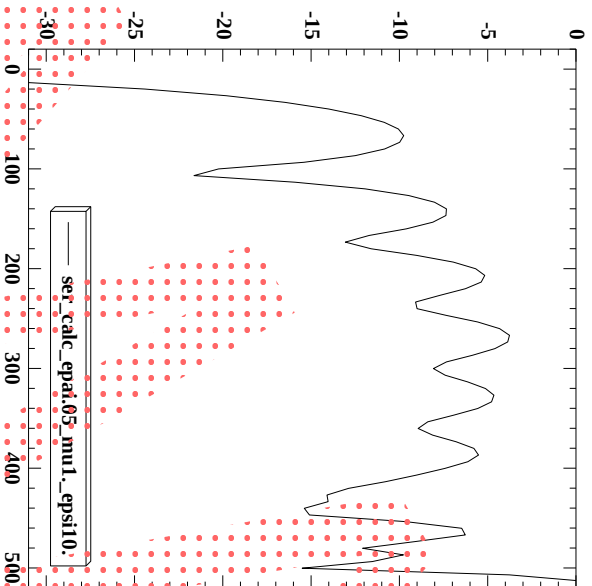
$\mu_r=1$; $f_{5pt} = 118\text{ MHz}$



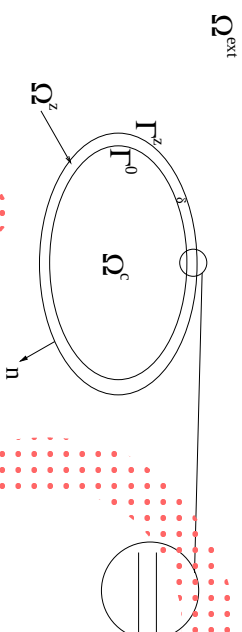
(n) $\delta=20\text{cm}$; $\epsilon_r=2$;

$\mu_r=1$; $f_{5pt} = 56\text{ MHz}$

g. Numerical results (ellipsoid)



h. Second application : Dielectric thin layer with $\sqrt{\varepsilon_r \mu_r} \gg 1$.



- the thickness δ is very small.
- $\sqrt{\varepsilon_r \mu_r} \gg 1$.
- in frequency domain : $\mathcal{Z}_x(\mathcal{J}) = i\omega\mu \frac{tg(\alpha\delta)}{\alpha} \vec{\mathcal{J}} \simeq i\omega\mu\delta\vec{j}$; où $\alpha = \frac{\sqrt{\varepsilon_r \mu_r}\omega}{c}$
- in time domain :

$$Z_{t,x}(\vec{j}) = -\delta \mu \frac{\partial \vec{j}}{\partial t}(t, x)$$

$$Z_{t,x}^{-1}(\vec{n} \wedge \vec{m}) = -\frac{1}{\delta \mu} \int_0^t (\vec{n} \wedge \vec{m}(t, x)) dt$$

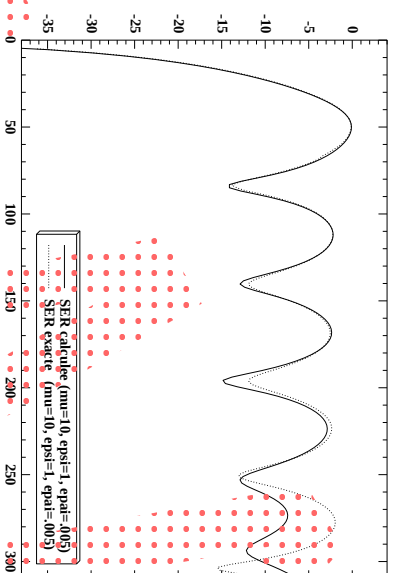
Spaces of $\vec{j}, \vec{m}$:

$$\begin{cases} V_{t,j} = H_\sigma^{1/2}(\mathbb{R}_+, TL^2(\Gamma)) \cap H_\sigma^{1/2}(\mathbb{R}_+, TH^{-1/2}(\text{div}, \Gamma)) \\ V_{t,m}^s = H_\sigma^{1/2}(\mathbb{R}_+, TH^{-1/2}(\text{div}, \Gamma)) \\ V_{t,m}^c = H_\sigma^{-1/2}(\mathbb{R}_+, TL^2(\Gamma)) \cap H_\sigma^{1/2}(\mathbb{R}_+, TH^{-1/2}(\text{div}, \Gamma)) \end{cases}$$

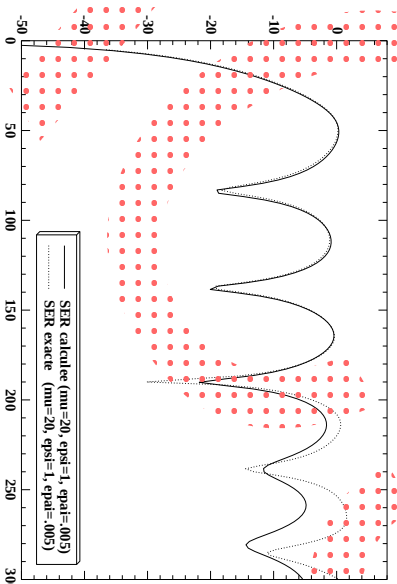
Theorem: The problem (S_v) has a unique solution in $V_{t,j}^s \times V_{t,m}^s$.

Theorem: The problem (C_v) has a unique solution in $V_{t,j}^s \times V_{t,m}^c$.

i. Numerical results (sphere)



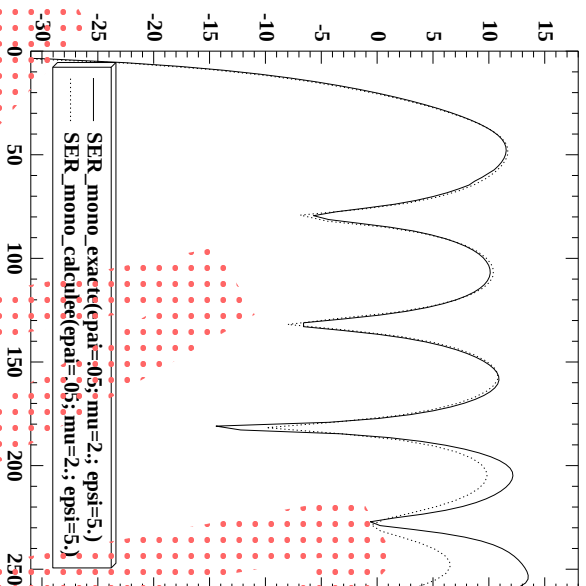
(q) $\delta=0.5\text{cm}$; $\epsilon_r=1$;
 $\mu_r=10$; $f_{5pt} = 118\text{ MHz}$



(r) $\delta=0.5\text{cm}$; $\epsilon_r=1$;
 $\mu_r=20$; $f_{5pt} = 56\text{ MHz}$

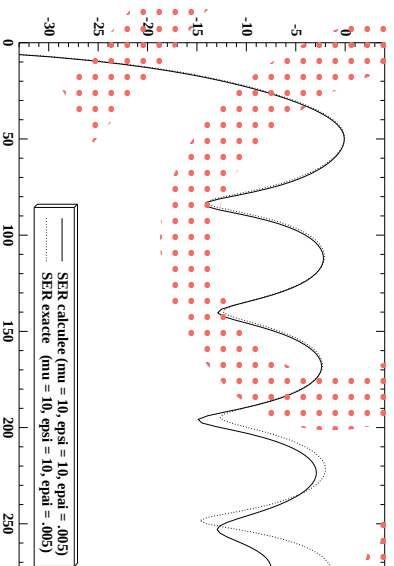
j. Extension

$$\mathbf{Z}_x(\mathcal{J}) = i\omega\mu\delta(\vec{\mathcal{J}}) - (i\omega)^3\varepsilon\mu^2\delta^3(\vec{\mathcal{J}})$$



(s) $\delta=5\text{cm}$; $\epsilon_r=5$;

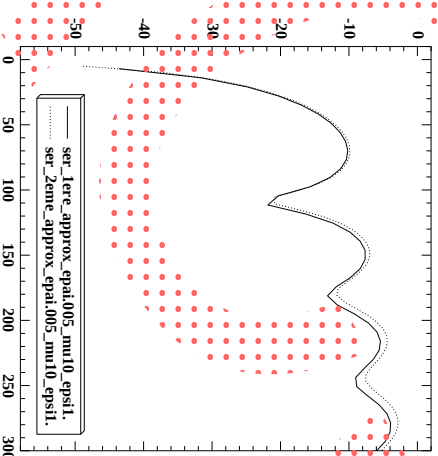
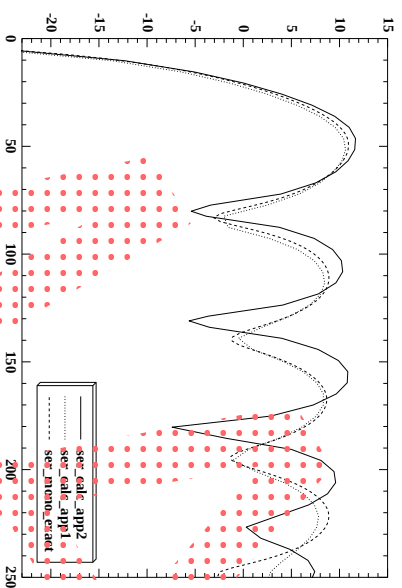
$\mu_r=2$; $f_{5pt} = 83$ MHz



(t) $\delta=0.5\text{cm}$; $\epsilon_r=10$;

$\mu_r=10$; $f_{5pt} = 30$ MHz

k. Comparison between the two applications

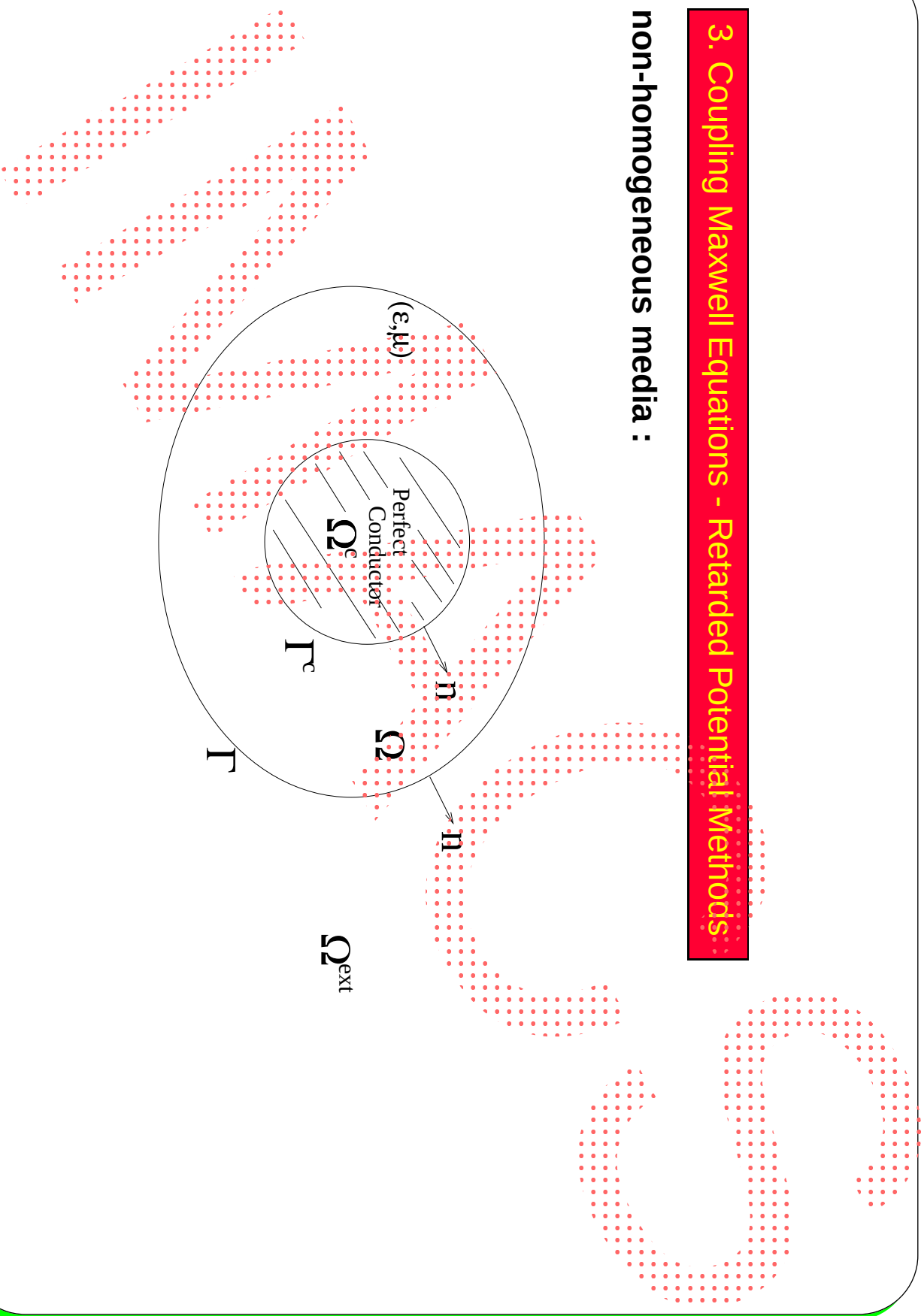


(u) $\delta=5\text{cm}$; $\epsilon_r=1$;
 $\mu_r=2$; $f_{5pt} = 185$
 MHz

(v) $\delta=0.5\text{cm}$;
 $\epsilon_r=1$; $\mu_r=20$;
 $f_{5pt} = 83$ MHz

3. Coupling Maxwell Equations - Retarded Potential Methods

non-homogeneous media :



a. Coupling

Maxwell equations in Ω + Integral representations in Ω^{ext} + continuity of the tangential components.

In frequency domain :

- Vincent LEVILLAIN : Two symmetric variational formulations (S) and (C). (Existence and uniqueness with ε and μ complex).

In time domain :

- Laurent Bounhoure : parallel work at BORDEAUX

Definition of the bilinear forms b_t^s and b_t^c

$$\begin{aligned}
 b_t^s(\vec{E}, \vec{j}, \vec{E}^t, \vec{j}^t) &= b_\Gamma(\vec{j}, \vec{m}, \vec{j}^t, \vec{m}^t) \\
 &\quad - \frac{1}{2} \langle \vec{m} \wedge \vec{n}, \vec{j}^t \rangle_{\sigma, \Gamma} - \frac{1}{2} \langle \vec{j} \wedge \vec{n}, \vec{m}^t \rangle_{\sigma, \Gamma} \\
 &\quad + \langle \varepsilon \frac{\partial \vec{E}}{\partial t}, \vec{E}^t \rangle_{\sigma, \Gamma} + \langle \mu \vec{curl}, \int_R \vec{E} dt; \vec{E}^t \rangle_{\sigma, \Gamma} \\
 b_t^c(\vec{E}, \vec{H}, \vec{E}^t, \vec{H}^t) &= b_\Gamma(\vec{j}, \vec{m}, \vec{j}^t, \vec{m}^t) \\
 &\quad + \langle \varepsilon \frac{\partial \vec{E}}{\partial t}, \vec{E}^t \rangle_{\sigma, \Gamma} + \langle \mu \vec{curl}, \int_R E dt, \vec{E}^t \rangle_{\sigma, \Gamma} \\
 &\quad + \langle \mu \frac{\partial \vec{H}}{\partial t}, \vec{H}^t \rangle_{\sigma, \Gamma} + \langle \varepsilon \vec{curl}, \int_R \vec{H} dt, \vec{H}^t \rangle_{\sigma, \Gamma}
 \end{aligned}$$

Definition of Spaces :

$$\left\{ \begin{array}{l} H^t = H_\sigma^1(\mathbb{R}_+, H(curl, \Omega)) \\ H_c^t = \left\{ \vec{E} \in H^t; \text{ such that } \vec{E} \wedge \vec{n} = \vec{0} \text{ on } \Gamma^c \right\} \\ V^t = H_\sigma^{\frac{1}{2}}(\mathbb{R}_+, H^{-\frac{1}{2}}(div, \Gamma)) \end{array} \right.$$

Variational Problem (S)

$$(S_v) \quad \begin{cases} \text{Find } (\vec{E}, \vec{j}) \in H_c^t \times V^t \text{ such that } \forall (\vec{E}^t, \vec{j}^t) \in H_c^t \times V^t \\ b_t^s(\vec{E}, \vec{j}, \vec{E}^t, \vec{j}^t) = L_t(\vec{m}^t, \vec{j}^t) \end{cases}$$

Variational Problem (C)

$$(C_v) \quad \begin{cases} \text{Find } (\vec{E}, \vec{H}) \in H_c^t \times H^t \text{ such that } \forall (\vec{E}^t, \vec{H}^t) \in H_c^t \times H^t \\ b_t^c(\vec{E}, \vec{H}, \vec{E}^t, \vec{H}^t) = L_t(\vec{m}^t, \vec{j}^t) \end{cases}$$

Existence and uniqueness of the solution

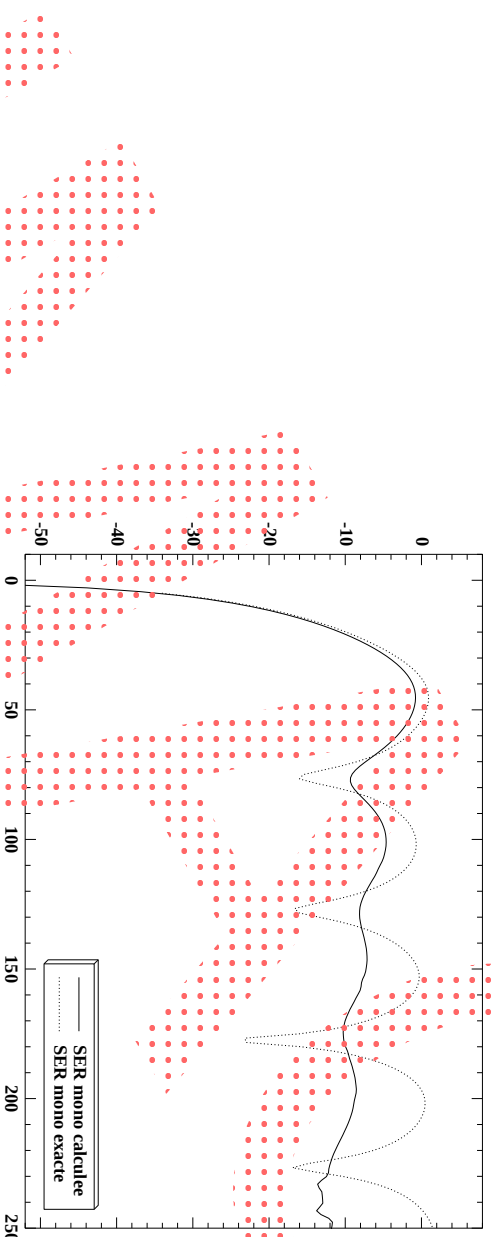
b. Numerical systems and results

$$\sum_{k=0}^N A^k \lambda^{n-k} + \sum_{k=0}^N C^k \nu^{n-k} - D \nu^n = b_1^n$$

$$\sum_{k=0}^N A^k \nu^{n-k} + \sum_{k=0}^N C^k \lambda^{n-k} + E(S^n - 2S^{n-1} + S^{n-2}) + F(S^n - D(\lambda^n - \lambda^{n-1})) = b_2^n$$

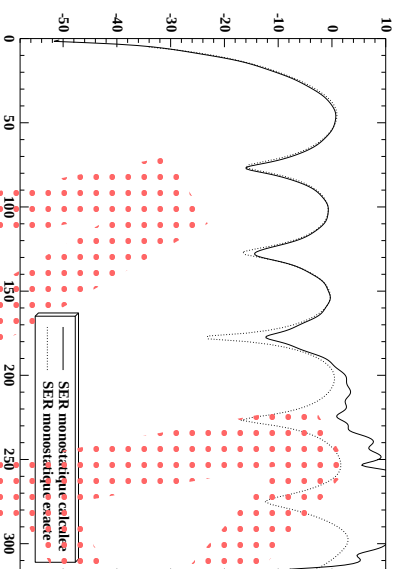
Unconditionally stable but not precise.

Sphere of radius 1m with a $\text{c}\epsilon = .5$, thickness of the layer = .2m, $\epsilon_r = 2$ and $\mu_r = 1$

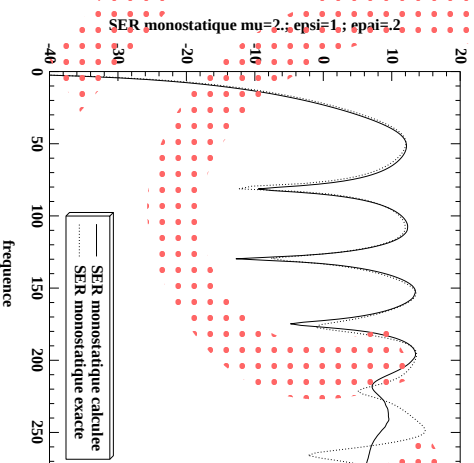


c. Newmark

$\alpha = .25$ and $\beta = .25$

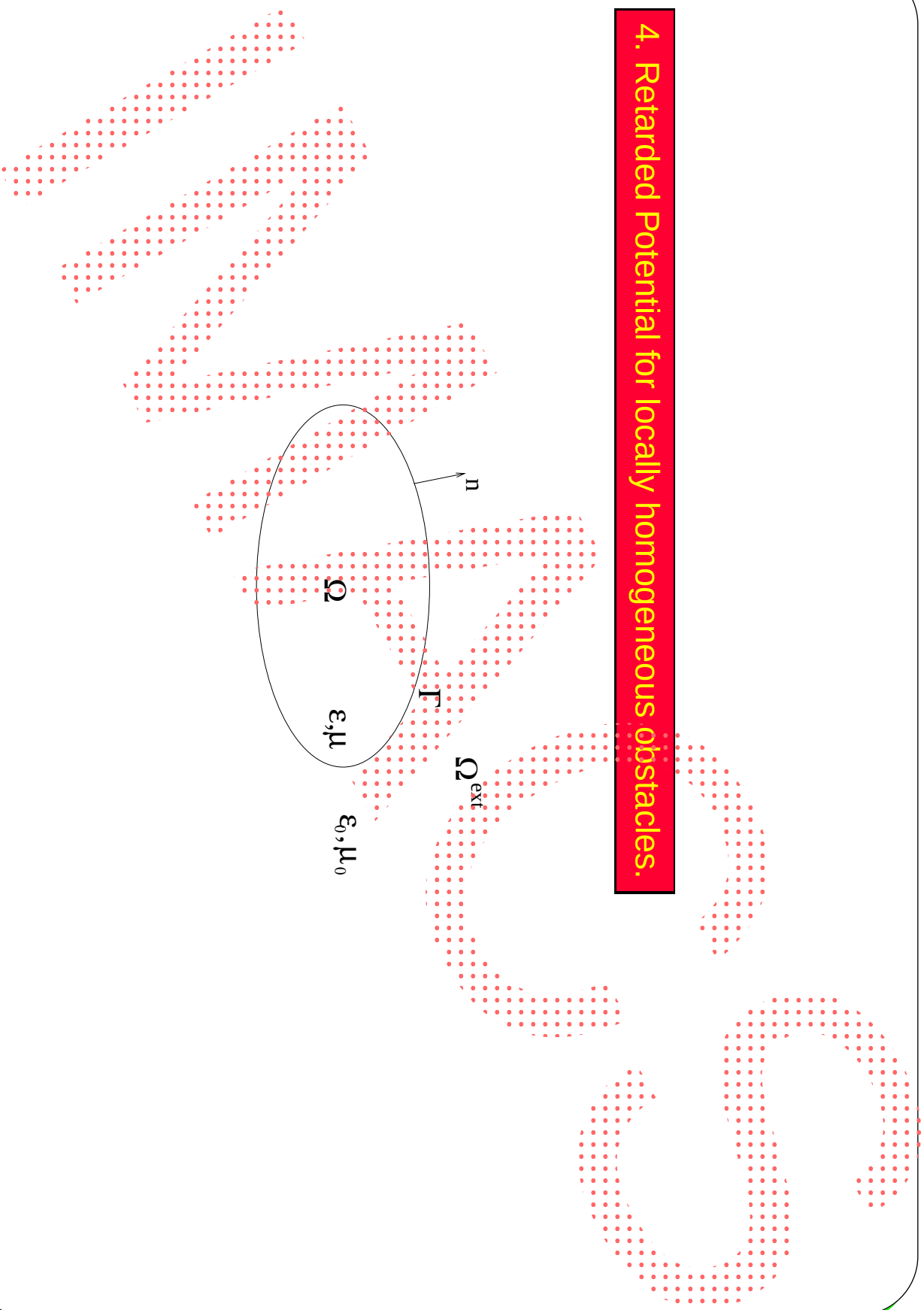


(w) sphere of 620 triangles : $R = 1m$, $\epsilon_r = 2$. and $\mu_r = 1..$



(x) sphere of 620 triangles : $R = 1m$, $\epsilon_r = 1$. and $\mu_r = 2..$

4. Retarded Potential for locally homogeneous obstacles.



a. Integral equations

- The total electrical field verifie in Ω^{ext} the previous integral representation with the same surface currents.
- Furthermore, we prolong the total electrical field in Ω by $\vec{0}$ in Ω^{ext} . Thanks to the theorem of integral representation, the electromagnetic field verifies the same representation with the same currents, but with the velocity

$$c' = c / \sqrt{\epsilon_r \mu_r}.$$

The continuity of the tangential components define the problem to solve.

b. Variational formulation

We denote by $P_{t,c'}^1$ and $P_{t,c'}^2$ the same operators $P_{t,c}^1$ and $P_{t,c}^2$ but with c' . We introduce

$$\begin{cases} V = H_o^{3/2}(\mathbb{R}_+, TH^{-1/2}(\text{curl}, \Gamma)) \\ W = H_o^{1/2}(\mathbb{R}_+, TH^{-1/2}(\text{div}, \Gamma)) \end{cases}$$

and

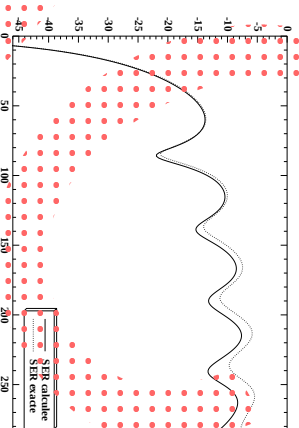
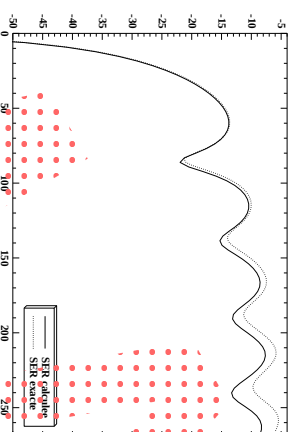
$$\begin{aligned} b_\Gamma^c(j, \vec{m}, j, \vec{m}^t) &= \langle P_{t,c}^1(j), j \rangle_{\sigma, \Gamma} + \langle P_{t,c}^2(\vec{m}), j \rangle_{\sigma, \Gamma} \\ &\quad + \frac{\varepsilon_0}{\mu_0} \langle P_{t,c}^1(\vec{m}), j \rangle_{\sigma, \Gamma^z} - \langle P_{t,c}^2(j), \vec{m} \rangle_{\sigma, \Gamma^z} \\ b_\Gamma^{c'}(j, \vec{m}, j, \vec{m}^t) &= \langle P_{t,c'}^1(j), j \rangle_{\sigma, \Gamma} + \langle P_{t,c'}^2(\vec{m}), j \rangle_{\sigma, \Gamma} \\ &\quad + \frac{\varepsilon_0}{\mu_0} \langle P_{t,c'}^1(\vec{m}), j \rangle_{\sigma, \Gamma^z} - \langle P_{t,c'}^2(j), \vec{m} \rangle_{\sigma, \Gamma^z} \\ b_t(j, \vec{m}, j, \vec{m}^t) &= b_\Gamma^c(j, \vec{m}, j, \vec{m}^t) + b_\Gamma^{c'}(j, \vec{m}, j, \vec{m}^t) \end{aligned}$$

We obtain the variational formulation :

$$(P_v) \left\{ \begin{array}{l} \text{For } (\vec{E}_\Gamma^i, \vec{H}_\Gamma^i) \in V \times V, \\ \text{Find } (\vec{j}, \vec{m}) \in W \times W \text{ such that } \forall (\vec{j}^t, \vec{m}^t) \in W \times W \\ b_t(\vec{j}, \vec{m}, \vec{j}^t, \vec{m}^t) = L_t(\vec{j}^t, \vec{m}^t) \end{array} \right.$$

Existence and uniqueness of the solution

c. Numerical results



(y) sphere of
320 triangles :

$R = 1m, \epsilon_r = 2.$ and

$\mu_r = 1..$

(z) sphere of
320 triangles :

$R = 1m, \epsilon_r = 1.$ and

$\mu_r = 2..$

d. General conclusions

Electromagnetic wave diffraction by :

- Perfect conductor obstacles (I.Terrasse and V.Lange).
- Impedance condition : (two practical problems).
- Coupling for non-homogeneous obstacles.
- Locally homogeneous obstacles : (Potential Retarded method)

e. Prospects

- Wires, antennas.
- Resistance, capacitor, ...
- Parallelization.
- Vectorization.